

Partial translation of JP2002-099019: paragraphs 0060-0062 (pages 5-6), and Fig. 15 (page 10)

[0060]

Fig. 15 is a conceptual diagram of a parallel link mechanism. The parallel link mechanism is formed of one sheet spring member to which link portions 5a, 5b, 5s, 5t are connected via deforming portion 5x. Deforming portion 5x is lower in rigidity than link portions 5a, 5b, 5s, 5t, and is easier to be subjected to elastic deformation. For example, deforming portion 5x includes only planes vertical to paper surface, and link portions 5a, 5b, 5s, 5t include planes parallel to paper surface and planes folded to become vertical to paper surface and L-shaped in cross-section to have rigidity.

[0061]

The parallel link mechanism is, as shown in Fig. 15 (b), configured in that it bends at deforming portion 5x, and movable link 5s opposing to fixed link 5t moves nearly in parallel with the extending direction of fixed link 5t.

[0062]

Fig. 9 (a) is an appearance view of camera shake correction unit 50 as viewed from the eyepiece side, and (b) is a partly sectional side view of the unit. Fig. 10 (a) is an enlarged perspective view of an essential portion of a link plate, (b) is a sectional view through the center of compensating lens, and (c) is a sectional view of a lock mechanism. Fig. 11 is an appearance view of camera shake correction unit 50 as viewed from the object lens side. Fig. 12 is an appearance view of camera shake correction

unit 50 without the base as viewed from the object lens side.

[Fig. 15]

